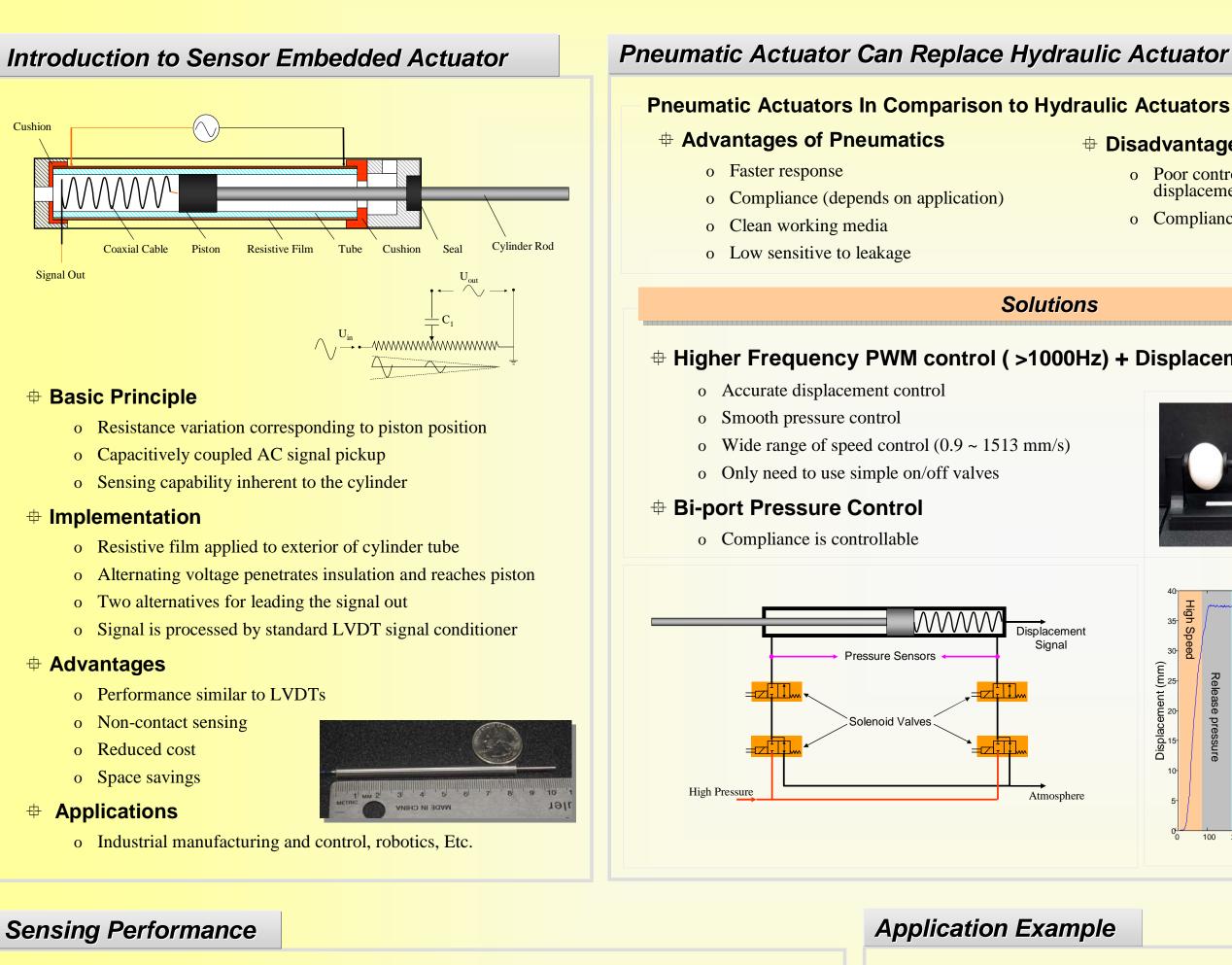
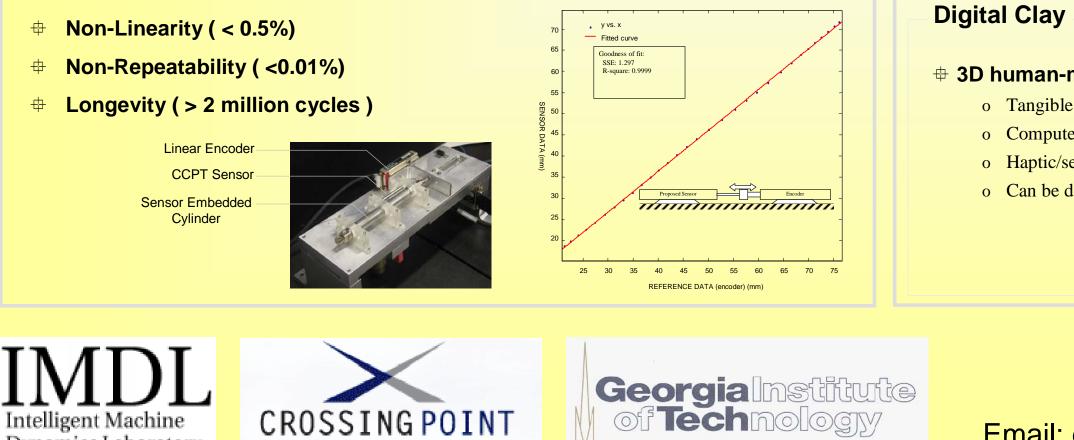


# **Position Sensing for Every Pneumatic Cylinder**

Haihong Zhu, Wayne J. Book Georgia Institute of Technology



Dynamics Laboratory



TECHNOLOGIES

o Only need to use simple on/off valves Bi-port Pressure Control o Compliance is controllable

o Compliance (depends on application)

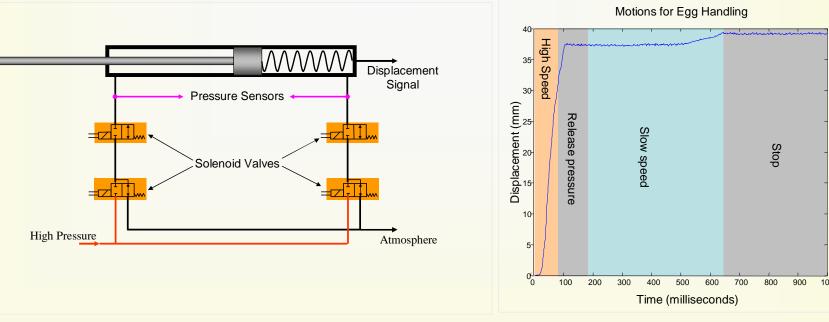
o Faster response

o Clean working media

o Low sensitive to leakage

o Accurate displacement control

o Smooth pressure control



o Computer controlled

o Haptic/semi-haptic style

# Pneumatic Actuator Can Replace Hydraulic Actuator

#### Future work

### Ubiquitous sensor embedded actuator

- Bensor in every actuator
  Sensor i
- Power via energy harvesting
- Sensing via wireless transmission

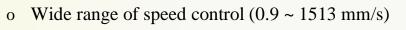


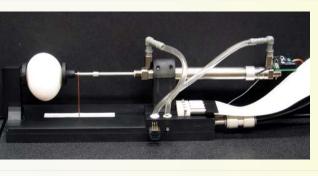
#### Higher Frequency PWM control ( >1000Hz) + Displacement Sensor

Disadvantages of Pneumatics

o Poor controllability (speed and displacement control)

o Compliance (depends on application)



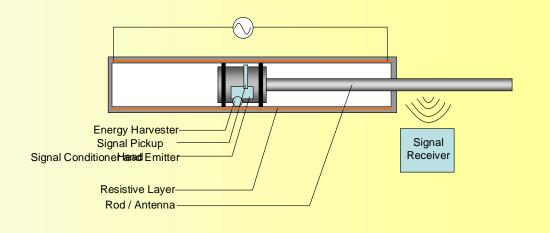


# Application Example

#### **4** 3D human-machine haptic interface

- o Tangible 3D shape/surface
- o Can be digitally edited / transferred





# **Digital Clay**

#### **Composition**

- o Micro miniature actuator-sensor arrays
- o Fluid power system
- o Control system

